

G4XS_KV10Z_XSG_IncrementalPWM

Processor Expert Example Project

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Overview

The purpose of this example project is to show how to use incremental PWM feature of Gen4 eXtremeSwitch. This feature allows to increment PWM duty of selected channels simultaneously by a given step. Utilization of this feature can be for example LED dimming or FAN speed regulation.

Requirements

Kinetis Design Studio 3.2.0 and newer

FRDM-KV10Z MCU board

FRDM-32XSG-EVB Gen4 eXtremeSwitch board

2 x channel load

USB cable

Setting up hardware

Target platform for this example is FRDM-KV10Z MCU board with FRDM-32XSG-EVB eXtremeSwitch board.

Chip select on FRDM-32XSG-EVB board has to be properly configured in such way that CSB0 pin is used. This can be achieved by switching **number 0 on SW2 switch** on the eSwitch board to **ON position**. The rest of CSB routes should remain in OFF position.



Figure 1 CSB Route Selection

In order to get the project successfully running you need to connect load to channels 1 and 3 on eSwitch.

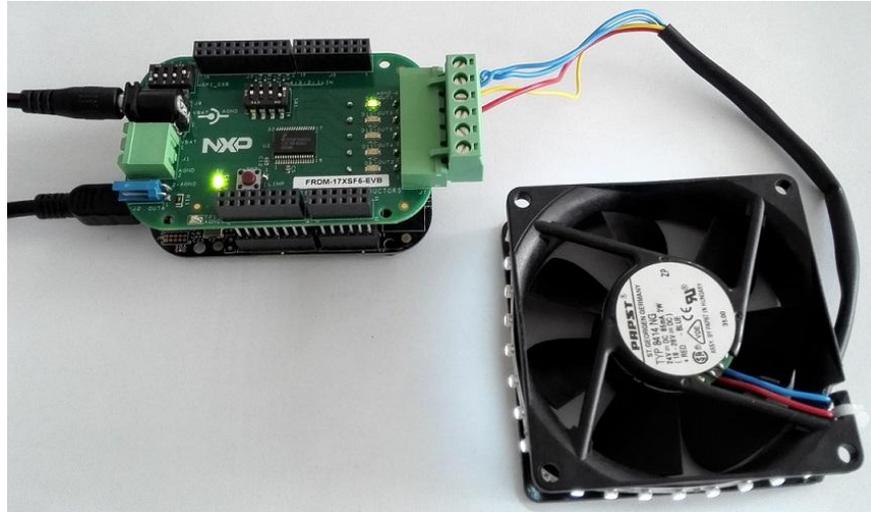


Figure 2 Channel Load

Set up OpenSDA connection between PC and MCU board with USB cable.



Figure 3 OpenSDA Connection

Setting up software

Make sure you have installed KDS 3.2.0 or newer which comes with Processor Expert support.

These components need to be imported to the Processor Expert Component Library.

- **SPI_Device** component (encapsulates SPI communication)
- **Gen4eXtremeSwitch** component (encapsulates eSwitch configuration)

Component	Description
▶ Kinetis	
▶ Legacy User Components	
▶ My Components	
▶ Software	
▶ User Components	
BC_MC32BC3770	Processor Expert support for battery charger MC32BC3770.
FRDM_BC3770	Processor Expert support for MC32BC3770 Charger Freedom Board
Gen4eXtremeSwitc	Processor Expert support for 32V eXtremeSwitch devices.
LVHBridge	Low voltage H-Bridge supporting MC34933, MPC17529, MPC17C724, M...
SPI_Device	Communication with SPI device placed on SPI bus
ThreePhaseMotorC	Three-Phase BLDC Motor Control
ThreePhasePre driv	Three Phase FET Pre-Driver GD3000/MC33937/MC34937

Figure 4 Processor Expert Component Library

Check that your OpenSDA connection has been set up.

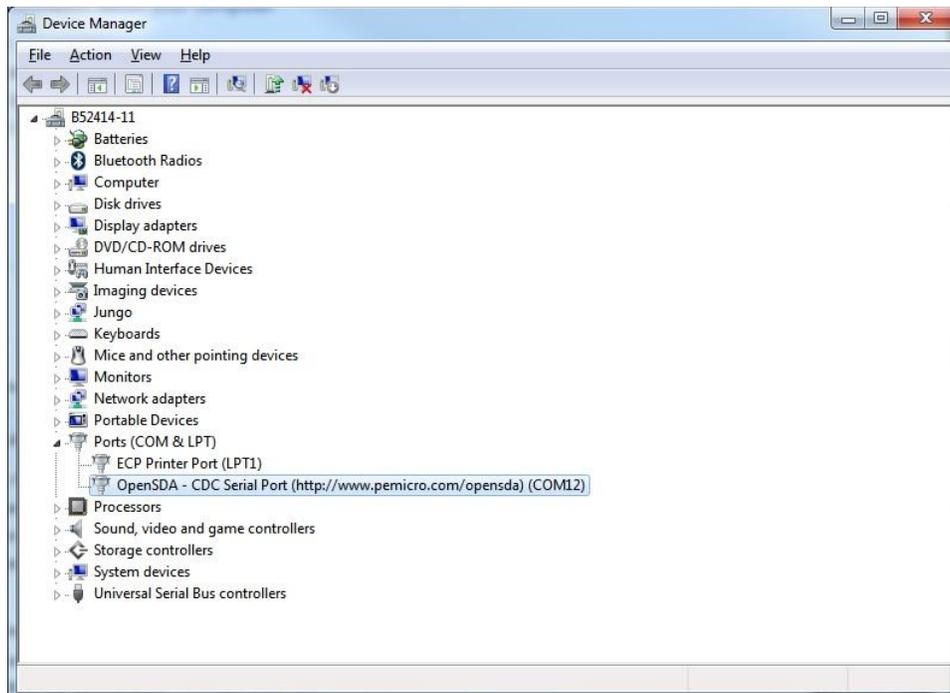


Figure 5 OpenSDA Virtual Port

Description

The example is preconfigured in the following way. FRDM-32XSG-EVB board is configured in **Gen4eXtremeSwitch** component, see Figure 7. SPI settings are configured separately in **SPIMaster_LDD** component, see Figure 8 and in inherited **CSpin1** component, see Figure 9. All components can be accessed in component tree, see Figure 6.

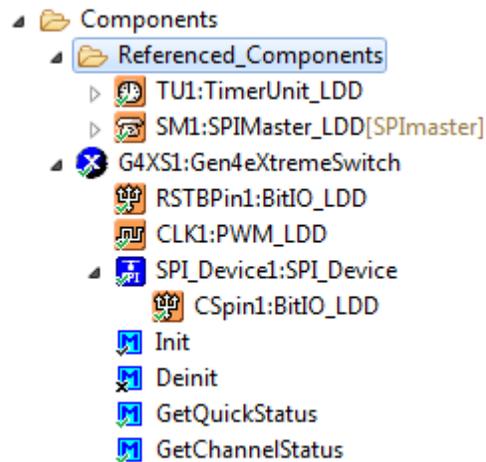


Figure 6 Component Tree

Channels 1 and 3 are enabled and configured in Gen4eXtremeSwitch component properties, see Figure 7. Both channels are enabled by default with PWM duty set to 32. This is dynamically changed later in the code. Watchdog timeout period is set to 128 ms. Make sure that if you modify the project, you still hold this watchdog period. All other features are set to default values except pin selection which follows **Error! Reference source not found.**

Component Name	G4XS1	
SPI Configuration	Parallel SPI	
Global Configuration		
RSTB Pin	ADC0_SE6/ADC1_SE1/ADC1_DP1/...	
External Clock Frequency	50000	D
CLK Pin	PTE25/FTM0_CH1/I2C0_SDA/EWM...	PTE25/FTM0_CH1/I2C0_SDA/EWM...
Watchdog Timeout	128 ms	
Direct Input Control	Disabled	
Current, Voltage and Temperature	Disabled	
Devices	1	
Device1		
Device Model	MC17XSF500	
SOA Mode	Single read	
Overtemperature Warning	115 °C	
HID Selection	Disabled	
OCHI Type	Default	
Global PWM Duty Cycle	0	D
Channels	6	
Output1	Enabled	Corresponds to channel with index...
PWM Output Control		
Global PWM	Disabled	
Channel Duty Cycle	32	D
Phase Selection	0°	
Pulse Skipping	Disabled	
Slew Rate Presc	1	
Output Initial State	On	
Direct Input Control	Disabled	
Open Load		
Open Load LED	Disabled	
OLON Deglitch	64 us	
Overcurrent		
OCLO Threshold	Low	
Advanced Current	Disabled	
Short OCHI	Disabled	
No OCHI	Disabled	
Output2	Disabled	Channel disabled.
Output3	Enabled	Corresponds to channel with index...
Output4	Disabled	Channel disabled.
Output5	Disabled	Channel disabled.
Output6	Disabled	Channel disabled.
Auto Initialization	yes	

Figure 7 G4XS Component Settings

SPI settings involve pin selection (MISO, MOSI, CLK and CSB). The first three pins are configured in **SPIMaster_LDD**, see Figure 8 and the last one is configured in **CSPin** component, see Figure 9, which is inherited by **SPI_Device** component.

Device	SPI0
Interrupt service/event	Enabled
▲ Settings	
▲ Input pin	Enabled
Pin	PTD3/SPI0_SIN/UART0_TX/FTM0_CH3/I2C0_SDA
▲ Output pin	Enabled
Pin	CMP0_IN0/PTC6/LLWU_P10/SPI0_SOUT/PDB0_EXTRG/UART0_RX/I..
▲ Clock pin	
Pin	PTC5/LLWU_P9/SPI0_SCK/LPTMR0_ALT2/CMP0_OUT/FTM0_CH2
Chip select list	0
▲ Attribute set list	1
▲ Attribute set 0	
Width	8 bits
MSB first	yes
Clock polarity	Low
Clock phase	Change on leading edge
Parity	None
Chip select toggling	no
Clock rate index	0
Delay after transfer index	0
CS to CLK delay index	0
CLK to CS delay index	0
Clock rate	0.667572 μ s
Delay after transfer	0.190735 μ s
CS to CLK delay	0.190735 μ s
CLK to CS delay	0.190735 μ s
▲ Initialization	
Auto initialization	yes

Figure 8 SPI Master Component Settings

Pin for I/O	ADC1_SE6/PTD6/LLWU_P15/SPI0_PCS3/UART0_RX/FTM0_CH0/FT...
Direction	Output
▲ Initialization	
Init. direction	Output
Init. value	0
Auto initialization	yes

Figure 9 Chip Select Pin Settings

Implementation itself is quite straightforward. In **main.c**, see Figure 10, is infinite main loop where all the logic of this example is situated.

1. At first duty value of both channels is incremented by 4 LSB until maximum duty value is reached.
2. After that duty value of both channels is decremented by 4 LSB until minimum duty value is reached.

```

int main(void)
/*lint -restore Enable MISRA rule (6.3) checking. */
{
    /* Write your local variable definition here */
    G4XS1_Error Error;
    uint8_t LSBStep[2] = {ids4LSB, ids4LSB};

    /** Processor Expert internal initialization. DON'T REMOVE THIS CODE!!! **/
    PE_low_level_init();
    /** End of Processor Expert internal initialization. **/

    for (;;) {
        while (1) { /* increments to maximum duty */
            Error = G4XS1_IncrementalPWMControl(0, idsPOSITIVE, LSBStep);
            if ((Error != ERR_OK) && (Error != ERR_MAX_DUTY)) {
                /* something went wrong */
            }
            for (uint8_t j = 0; j < 10; j++) { /* waits for 200 ms */
                WaitMS(20);
                G4XS1_FeedWatchdog();
            }
            if (Error == ERR_MAX_DUTY) {
                break;
            }
        }

        while (1) { /* decrements to minimum duty */
            Error = G4XS1_IncrementalPWMControl(0, idsNEGATIVE, LSBStep);
            if ((Error != ERR_OK) && (Error != ERR_MIN_DUTY)) {
                /* something went wrong */
            }
            for (uint8_t j = 0; j < 10; j++) { /* waits for 200 ms */
                WaitMS(20);
                G4XS1_FeedWatchdog();
            }
            if (Error == ERR_MIN_DUTY) {
                break;
            }
        }
    }
}

```

Figure 10 Content of main.c

Note that **FeedWatchdog()** has to be called periodically even when some delay is required.

Import the example project

Pre-requisites such as needed components are assumed to be imported already. If that is correct, you can approach to importing of the example project.

1. In KDS click on the ***File / Import***.
2. Choose ***General / Existing Projects into Workspace***.
3. Click ***Browse to select root directory*** with your downloaded example projects.
4. ***Select project*** named **G4XS_KV10Z_XSG_IncrementalPWM** and click ***Finish*** to complete the process.
5. Now the example project should be copied to your workspace and ready to run.

Build and Debug

In order to build and run the project you need to ***generate code*** at first. Then you can ***build*** the project usual way. If the build is successful, ***debug and run*** the project.